

If Worse Comes to Worst: Systematic Stress Tests with Discrete and Other Non-normal Distributions

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- ① First Generation Stress Tests
- ② Second Generation Stress Tests
- ③ Stress Testing with Generalised Scenarios
- ④ How to Solve It
- ⑤ Applications

Outline

- 1 First Generation Stress Tests
- 2 Second Generation Stress Tests
- 3 Stress Testing with Generalised Scenarios
- 4 How to Solve It
- 5 Applications

Purpose of Stress Testing: Complement statistical risk measurement

- Statistical risk measurements: What are probs of big losses?
Stress Testing: Which scenarios lead to big losses?
Derive risk reducing action.
- Statistical risk measurement: Assume fixed model.
Stress Testing: Consider alternative risk factor distribution.
Address model risk.

Requirements on stress scenarios (Basel II)

- Plausibility
- Severity
- Suggestive of risk reducing action

See Basel Principles of Sound Stress Testing

Framework

Reference risk factor distribution ν ,
Portfolio loss function L ,
both on risk factor space $\Omega \subset \mathbb{R}^n$.

First Generation Stress Tests: Hand-picked Point Scenarios

- A small number of scenarios is picked by hand, ideally involving heterogeneous groups of experts.
 $A = \{\mathbf{r}^1, \mathbf{r}^2, \dots, \} \subset \Omega$: a small set of hand-picked scenarios.
- Find worst case scenario and worst case loss in A :

$$\max_{\mathbf{r} \in A} L(\mathbf{r})$$

- Worst case loss over A is a coherent risk measure.
- Examples: SPAN rules.

Pitfalls of First Generation Stress Tests

- 1 Neglecting severe but plausible scenarios
- 2 Considering too implausible scenarios

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Second Generation Stress Tests: Systematic Point Scenario Analysis

- **Measure of plausibility** for point scenarios:

$$\text{Maha}(\mathbf{r}) := \sqrt{(\mathbf{r} - \mathbb{E}(\mathbf{r}))^T \cdot \Sigma^{-1} \cdot (\mathbf{r} - \mathbb{E}(\mathbf{r}))},$$

where Σ is covariance matrix of risk factor distribution ν .

- Choose as scenario set A

$$\text{Ell}_h := \{\mathbf{r} : \text{Maha}(\mathbf{r}) \leq h\},$$

where $h \in [0, \infty]$ is the plausibility threshold.

“Size of multivariate risk factor jump, measured in standard deviations.”

Advantages of Systematic Stress Testing with Point Scenarios

All three requirements on stress testing are met:

- Do not miss plausible but severe scenarios.
- Do not consider scenarios which are too implausible.
- Worst case scenario over Ell_h gives information about portfolio structure and suggests risk reducing action.

Problems of Systematic Stress Testing with Point Scenarios

- ① optimisation problem sometimes hard to solve.
- ② Maha does not take into account fatness of tails.
- ③ How choose scenario set for non-elliptical risk factor distributions ν ?
- ④ $\text{MaxLoss}_{\text{Ell}_k}$ depends on choice of coordinates.
- ⑤ $\text{MaxLoss}_{\text{Ell}_k}$ is not law-invariant: Portfolios L_1, L_2 might have the same profit/loss distribution but different $\text{MaxLoss}_{\text{Ell}_k}$.
- ⑥ Model risk is not addressed.

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Generalised Scenarios

Generalised scenario: Probability distribution on (Ω, \mathbb{F}) .

- Interpretation 1:
Generalisation of point scenarios,
which have support concentrated on one point.
- Interpretation 2:
Risk factor distributions alternative to the prior ν .
Model risk.

Plausibility of Generalised Scenarios

- **Measure of plausibility:** relative entropy
(I -divergence, information gain, Kullback-Leibler distance)

$$I(Q||\nu) := \begin{cases} \int \log \frac{dQ}{d\nu}(\mathbf{r}) dQ(\mathbf{r}) & \text{if } Q \ll \nu \\ +\infty & \text{if } Q \not\ll \nu \end{cases}$$

- **Scenario set:** Instead of ellipsoid take
Kullback-Leibler sphere in the space of distributions

$$S(\nu, k) := \{Q : I(Q||\nu) \leq k\}.$$

Worst Case Scenario

- **Severity of scenarios:** Instead of $L(\mathbf{r})$ take $\mathbb{E}_Q(L)$
- Generalised MaxLoss:

$$\sup_{Q \in \mathcal{S}(\nu, k)} \mathbb{E}_Q(L) =: \text{MaxLoss}_k(L)$$

If it exists, call scenario achieving MaxLoss: \bar{Q} .

Advantages of Systematic Stress Testing with Generalised Scenarios

- 1 Relative entropy does take into account fatness of tails of ν .
- 2 Scenario set is naturally defined for non-elliptical risk factor distributions ν .
- 3 MaxLoss_k does not depend on choice of coordinates.
- 4 MaxLoss_k is law-invariant: Portfolios L_1, L_2 with the same profit/loss distribution have the same MaxLoss_k .
- 5 Model risk is addressed:
Generalised scenarios are alternatives to prior risk factor distribution ν .

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The Basic Tool

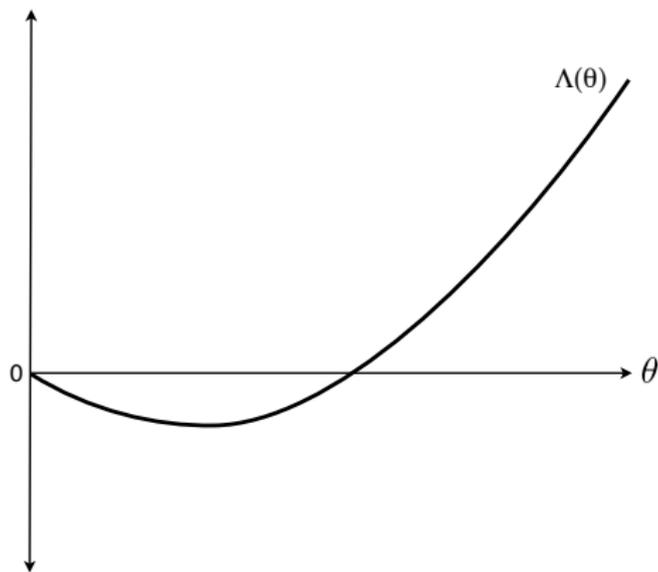
- Tool from large deviations theory for solving explicitly the optimisation problem $\sup_{Q \in \mathcal{S}(\nu, k)} \mathbb{E}_Q(L)$:

$$\Lambda(\theta) := \log \left(\int e^{\theta L(\mathbf{r})} d\nu(\mathbf{r}) \right).$$

- $\theta_{\max} := \sup\{\theta : \Lambda(\theta) < +\infty\}$
- $\Lambda(\theta)$ is the analogue of the log-partition function $Z(\beta)$ from statistical mechanics.

Basic Properties of the Λ -function

- $\Lambda(0) = 0$.
- Λ is convex.



Solution of Worst Case: The Generic Case

Theorem

- Except in the pathological cases (i), (ii), (iii) below, the equation

$$\theta \Lambda'(\theta) - \Lambda(\theta) = k, \quad (1)$$

has always a unique positive solution $\bar{\theta}$.

- The generalised worst case scenario \bar{Q} is the distribution with ν -density

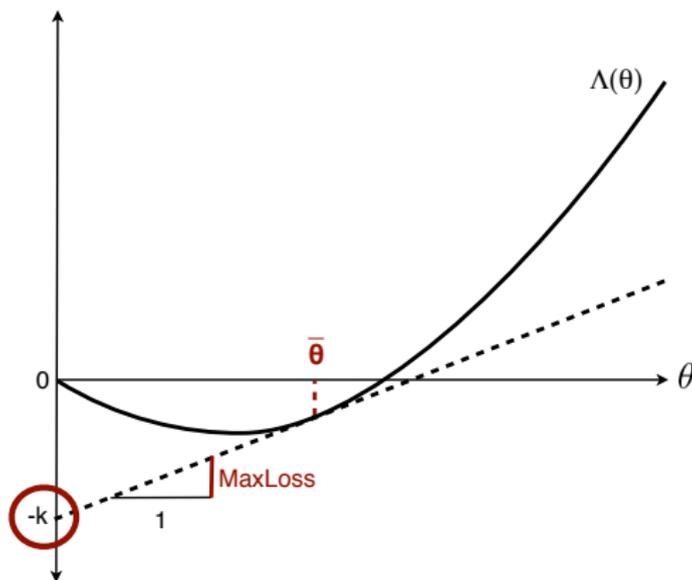
$$\frac{d\bar{Q}}{d\nu}(\mathbf{r}) := \frac{e^{\bar{\theta}L(\mathbf{r})}}{\int e^{\bar{\theta}L(\mathbf{r})} d\nu(\mathbf{r})} = e^{\bar{\theta}L(\mathbf{r}) - \Lambda(\bar{\theta})}, \quad (2)$$

- The generalised Maximum Loss achieved in the generalised worst case scenario \bar{Q} is

$$\mathbb{E}_{\bar{Q}}(L) = \Lambda'(\bar{\theta}).$$

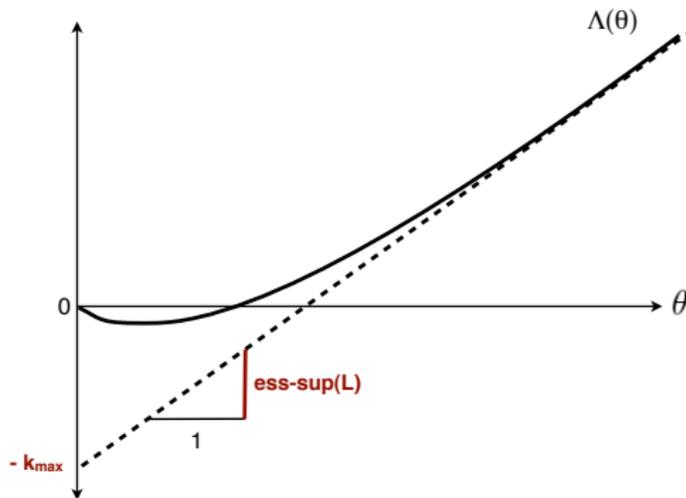
Practical Calculation of Worst Case

- 1 Calculate $\Lambda(\theta)$. (Evaluate n -dimensional integral.)
- 2 Starting from the point $(0, -k)$, lay a tangent to $\Lambda(\theta)$ curve.
- 3 Worst case loss is given by the slope of the tangent.
- 4 $\bar{\theta}$ is θ -coordinate of tangent point.
- 5 Worst case scenario is distribution with density $\frac{d\bar{Q}}{d\nu}(\mathbf{r}) = e^{\bar{\theta}L(\mathbf{r}) - \Lambda(\bar{\theta})}$.



Worst Case: The Pathological Cases

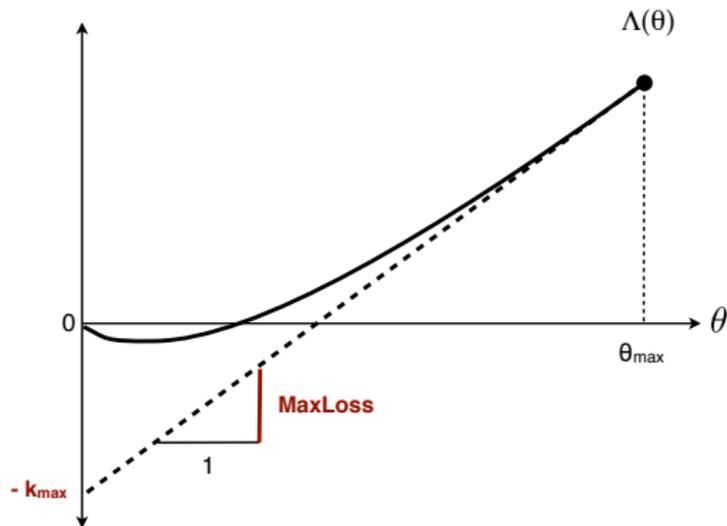
- (i) If $\text{ess sup}(L)$ is finite, and $k \geq -\log(\nu(\{\mathbf{r} : L(\mathbf{r}) = \text{ess sup}(L)\}))$, then $\text{MaxLoss}(k) = \text{ess sup}(L)$.



- (ii) If $\theta_{\max} = 0$ then $\text{MaxLoss}(k) = \infty$ for all $k > 0$.

Worst Case: Pathological Cases cont'd

- (iii) If θ_{\max} , $\Lambda(\theta_{\max})$, and $\Lambda'(\theta_{\max})$ are all finite and $k > k_{\max} := \theta_{\max} \Lambda'(\theta_{\max}) - \Lambda(\theta_{\max})$, then $\text{MaxLoss}(k) = (k + \Lambda(\theta_{\max})) / \theta_{\max}$.



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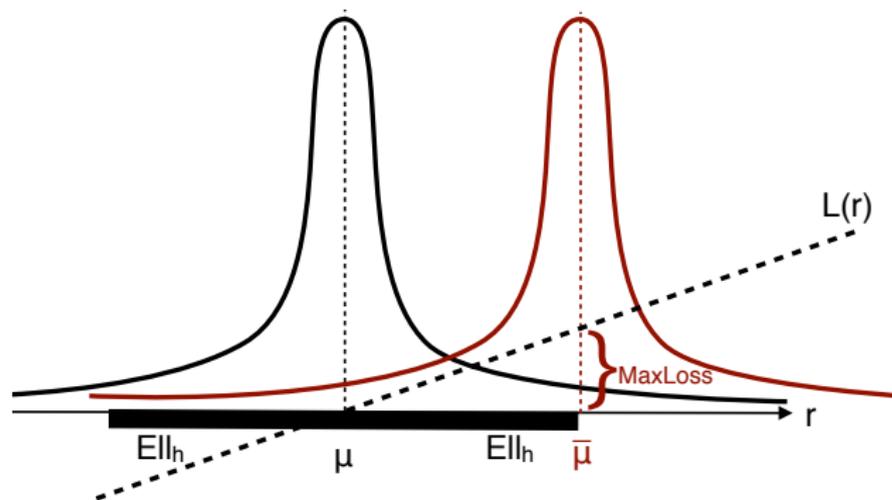
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One normal risk factor, linear portfolio

Loss linear function of 1 risk factor: $L(r) = l(\mu - r)$,
 $\nu \sim N(\mu, \sigma^2)$.

Worst case scenario: $\bar{Q} \sim N(\bar{\mu}, \sigma^2)$ where $\bar{\mu} = \mu + h\sigma \text{sgn}(l)$ and
 $h = \sqrt{2k}$.

Worst case loss: $\mathbb{E}_{\bar{Q}}(L) = h\sigma|l| = h\sqrt{l\sigma^2 l}$.



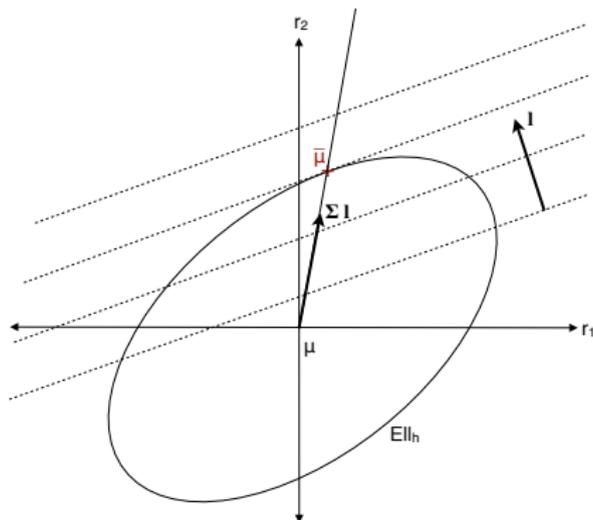
More normal risk factors, linear portfolio

Loss linear function of n risk factors: $L(r) = \mathbf{I}^T(\boldsymbol{\mu} - r)$,
 $\nu \sim N(\boldsymbol{\mu}, \boldsymbol{\Sigma})$.

Λ quadratic: $\Lambda(\theta) = \mathbf{I}^T \boldsymbol{\Sigma} \mathbf{I} \theta^2 / 2$.

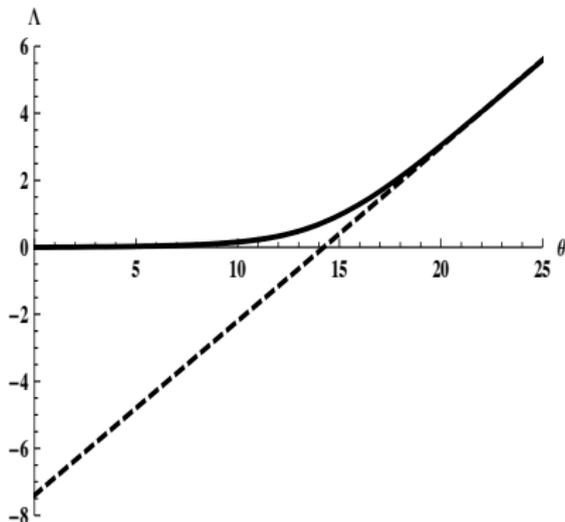
Worst case scenario: $\bar{Q} \sim N(\bar{\boldsymbol{\mu}}, \boldsymbol{\Sigma})$ with $\bar{\boldsymbol{\mu}} = \boldsymbol{\mu} - \frac{h}{\sqrt{\mathbf{I}^T \boldsymbol{\Sigma}}} \boldsymbol{\Sigma} \mathbf{I}$ where $h = \sqrt{2k}$.

Worst case loss: $\mathbb{E}_{\bar{Q}}(L) = h\sqrt{\mathbf{I}^T \boldsymbol{\Sigma} \mathbf{I}}$.



Stressed transition probabilities

- $\Omega = \{0, 1, \dots, n\}$: rating classes.
- $\mathbf{p} = (p_1, \dots, p_n)$: estimated transition probabilities
- $\mathbf{l} = (l_1, \dots, l_n)$: loss caused by transitions
- $\Lambda(\theta) = \log \left(\sum_{j=1}^n p_j \exp(\theta l_j) \right)$.
- Worst case transition probabilities: $\bar{p}_i = \frac{p_i \exp(\bar{\theta} l_i)}{\sum_{j=1}^n p_j \exp(\bar{\theta} l_j)}$.

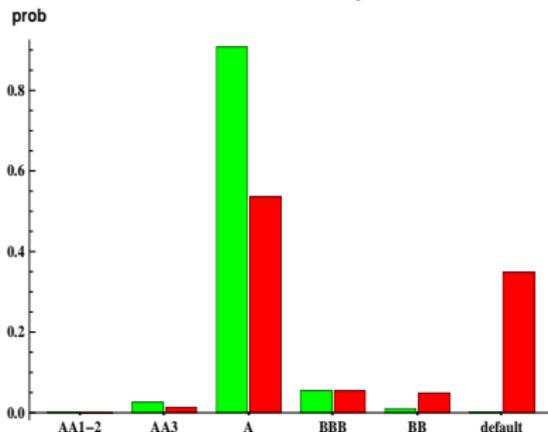


Numerical example: A-rated bond

	AA1-2	AA3	A	BBB	BB	Default
loss from transitions [%]	-3.20%	-1.07%	0.00%	3.75%	15.83%	51.80%
est'd trans. prob. [%]	0.09	2.60	90.75	5.50	1.00	0.06
worst c. trans. prob. [%]	0.036	1.34	53.53	5.37	4.91	34.8

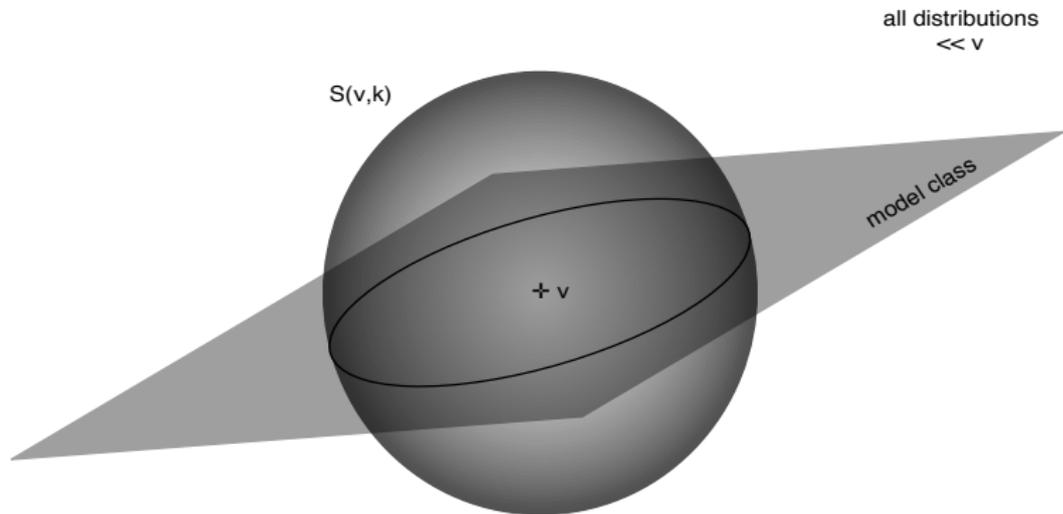
Expected loss from transitions under est'd probs: 0.37%

Expected loss from transitions under worst case probs at $k=2$: 19.07%



Model Risk

- estimation error: wrong distribution parameters
- model misspecification: wrong model class
- $\sup_{Q \in S(\nu, k)} \mathbb{E}_Q(L)$ quantifies effects of both on expected loss.



Summary

- 1 Calculate $\Lambda(\theta) := \log \left(\int e^{\theta L(\mathbf{r})} d\nu(\mathbf{r}) \right)$.
- 2 Starting from the point $(0, -k)$, lay a tangent to $\Lambda(\theta)$ curve.
- 3 Worst case loss is given by the slope of the tangent.
- 4 $\bar{\theta}$ is θ -coordinate of tangent point.
- 5 Worst case scenario is distribution with density $\frac{d\bar{Q}}{d\nu}(\mathbf{r}) = e^{\bar{\theta}L(\mathbf{r}) - \Lambda(\bar{\theta})}$.

